

Print file information:

```
RUN_IN_PLACE=no
EMC2_DIR=
EMC2_BIN_DIR=/usr/bin
EMC2_TCL_DIR=/usr/share/emc/tcl
EMC2_SCRIPT_DIR=
EMC2_RTLIB_DIR=/usr/lib/emc2/modules
EMC2_CONFIG_DIR=
EMC2_LANG_DIR=/usr/share/emc/tcl/mmsgs
INIVAR=inivar
HALCMD=halcmd
EMC2_EMCSH=/usr/bin/wish8.5
EMC2 - 2.4.6
Machine configuration directory is '/home/mark/emc2/configs/Sherline3Axis'
Machine configuration file is 'Sherline3Axis_inch.ini'
INIFILE=/home/mark/emc2/configs/Sherline3Axis/Sherline3Axis_inch.ini
PARAMETER_FILE=stepper.var
EMCMOT=motmod
EMCIO=io
TASK=milltask
HALUI=
DISPLAY=axis
NML_FILE=
Starting EMC2...
Starting EMC2 server program: emcsvr
Loading Real Time OS, RTAPI, and HAL_LIB modules
Starting EMC2 IO program: io
Shutting down and cleaning up EMC2...
Killing task emcsvr, PID=3569
Removing HAL_LIB, RTAPI, and Real Time OS modules
Removing NML shared memory segments
Cleanup done
```

Debug file information:

```
hal_parport: dlopen: /usr/lib/emc2/modules/hal_parport.so: cannot open shared
object file: No such file or directory
standard_pinout.hal:5: /usr/bin/rtapi_app exited without becoming ready
standard_pinout.hal:5: insmod failed, returned -1
3569
  PID TTY          STAT       TIME COMMAND
Stopping realtime threads
Unloading hal components
```