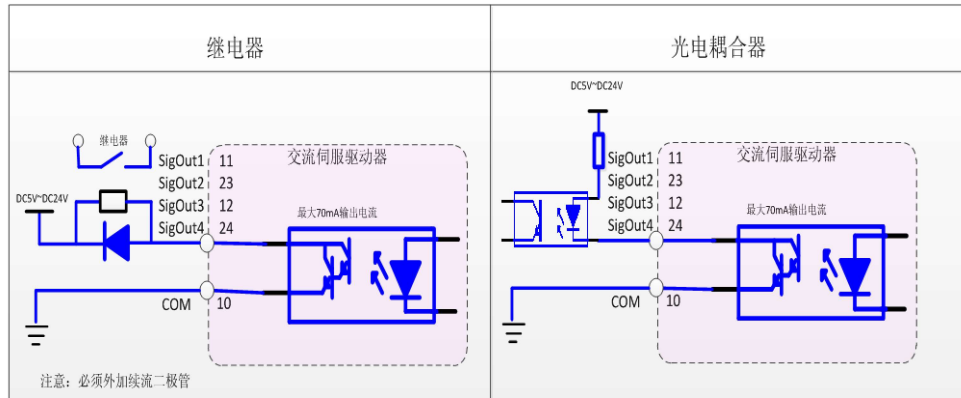


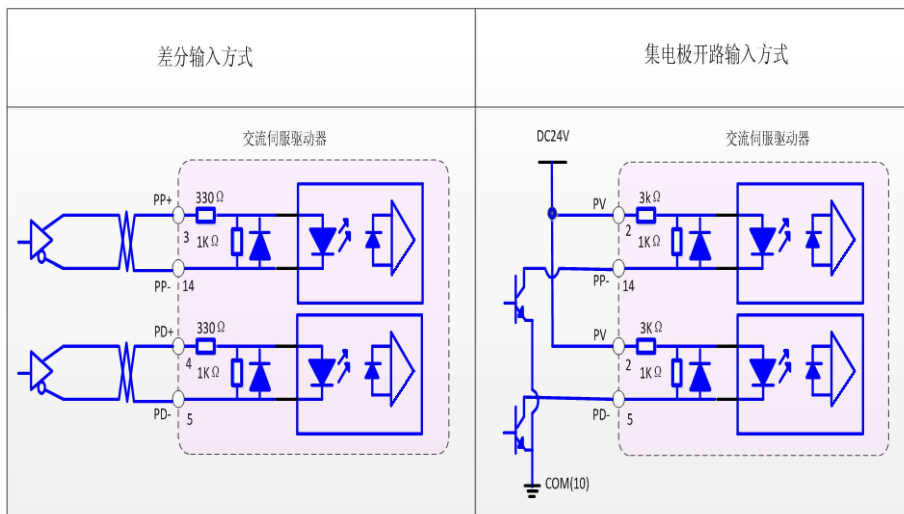
●如果负载是继电器等电感性负载，必须在负载两端反并联续流二极管。如果续流二极管接反，可能导致伺服驱动器损坏。

If the load is relay and inductive load, the load must be both ends against parallel fly-wheel diode. If fly-wheel diode picks back, may cause damage to the servo driver.



3. 位置脉冲指令接口 Position pulse command interface

有差分驱动和单端驱动两种接法，推荐差分驱动接法。接线宜采用双绞线。A differential drive and single end drive have two connections, recommend differential drive connection. Connection appropriate USES twisted-pair cable



●在差分输入方式下，建议采用 AM26LS31 类似线驱动器；为了使传送的脉冲数据有很好的抗干扰能力，建议采用差分驱动方式；最大输入脉冲频率 500kHz(kpps) 。In the differential input mode, it is recommended AM26LS31 similar line drive; In order to make the transfer of pulse data has good anti-interference ability, it is suggested that the differential drive way; Maximum input pulse frequency 500 KHZ (KPPS).