

**CURRENT
ARRANGEMENT -
Single Rotary Enc
(...encoder.rot...)**

axis.0.amp-enable-out
pid.x.enable
pwmgen.00.enable

axis.0.motor-pos-fb
encoder.rot.position

pid.x.index-enable
axis.0.index-enable
encoder.rot.index-enable

axis.0.motor-pos-cmd

not connected

Other
inputs/params:
P
I
D
FF1

PID - Rotary Enc
pid.x.index-enable
pid.x.enable
pid.x.command
pid.x.command-deriv
pid.x.feedback-deriv
pid.x.feedback
pid.x.output

Scale
10V

pwmgen.00.value

