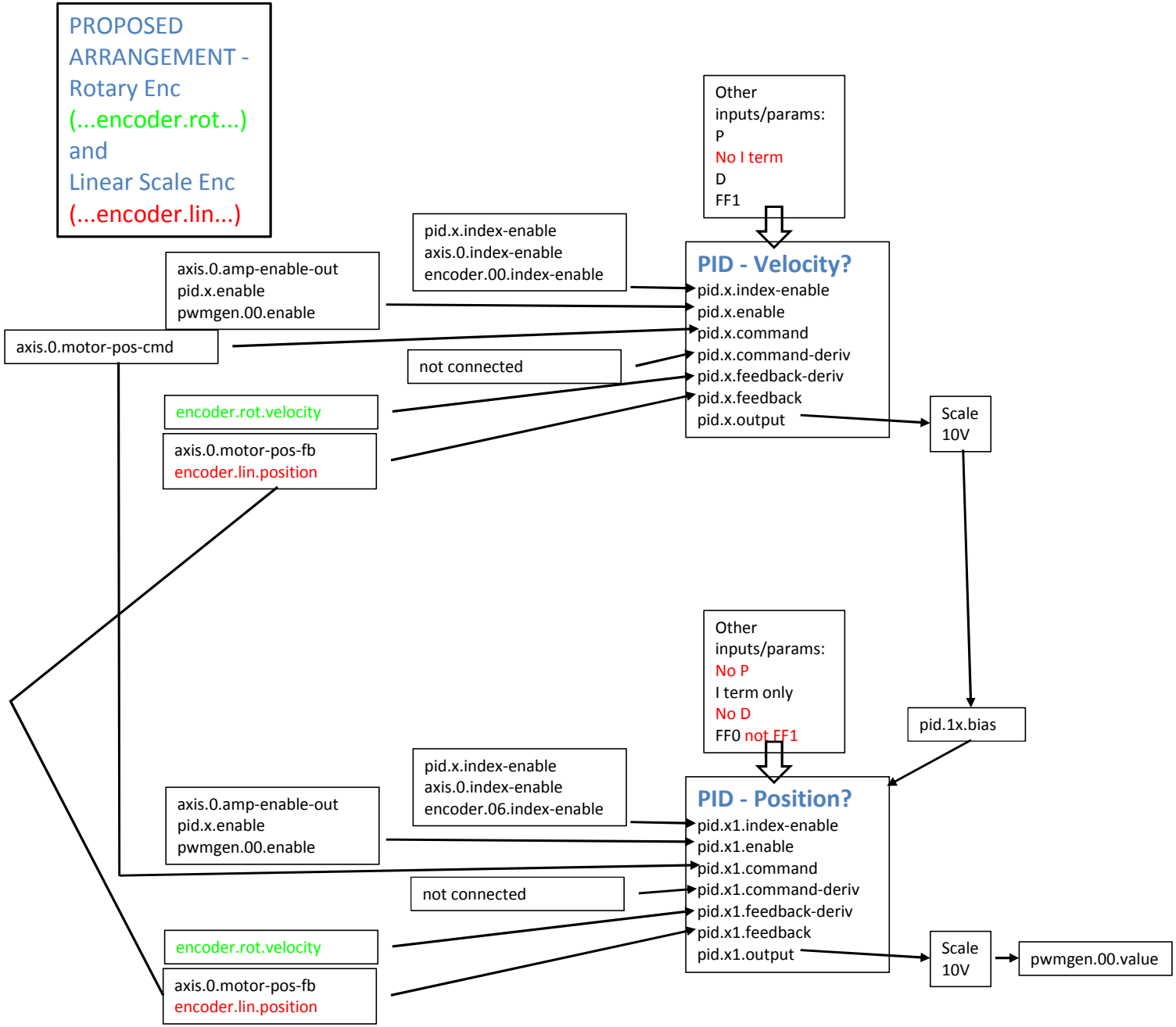
PROPOSED ARRANGEMENT - Rotary Enc (...encoder.rot...) and Linear Scale Enc (...encoder.lin...)
Other inputs/params:
P
No I term
D
FF1
pid.x.index-enable
axis.0.index-enable
encoder.00.index-enable
axis.0.amp-enable-out
pid.x.enable
pwmgen.00.enable
axis.0.motor-pos-cmd
not connected
encoder.rot.velocity
axis.0.motor-pos-fb
encoder.lin.position
PID - Velocity?
pid.x.index-enable
pid.x.enable
pid.x.command
pid.x.command-deriv
pid.x.feedback-deriv
pid.x.feedback
pid.x.output
Scale 10V
pid.1x.bias
Other inputs/params:
No P
I term only
No D
FF0 not FF1
pid.x.index-enable
axis.0.index-enable
encoder.06.index-enable
axis.0.amp-enable-out
pid.x.enable
pwmgen.00.enable
not connected
encoder.rot.velocity
axis.0.motor-pos-fb
encoder.lin.position
PID - Position?
pid.x1.index-enable
pid.x1.enable
pid.x1.command
pid.x1.command-deriv
pid.x1.feedback-deriv
pid.x1.feedback
pid.x1.output
Scale 10V
pwmgen.00.value