

Config sample lines from hal file:

loadrt hostmot2

loadrt hm2_eth board_ip="192.168.1.121" config="num_encoders=1 num_pwmgens=0 num_stepgens=3 sserial_port_0=21xxxxxx"

Notes:

board_ip="192.168.1.121"

The default IP address of the 7i76e
Its suggested to use the 10.10.10.10 IP address for LinuxCNC so you don't end up with the real time Ethernet IP address range, overlapping a DHCP pool of local network addresses.
(set W3 up instead of down to use 10.10.10.10)

num_encoders=1

see man hostmot2 for additional details

num_pwmgens=0

see man hostmot2 for additional details

num_stepgens=3

see man hostmot2 for additional details

sserial_port_0=21xxxxxx

The first digit (2) selects the software mode from the 7i76e itself,
The second digit (1) selects the software mode of the connected SSerial device i.e. the 7i73

7i76e supports 3 Software modes:

MODE 0 I/O only mode (32 bits of input data, 16 bit of output data)

MODE 1 I/O plus analog input mode (32 bits of input data, 16 bits of output data, 4analog input channels)

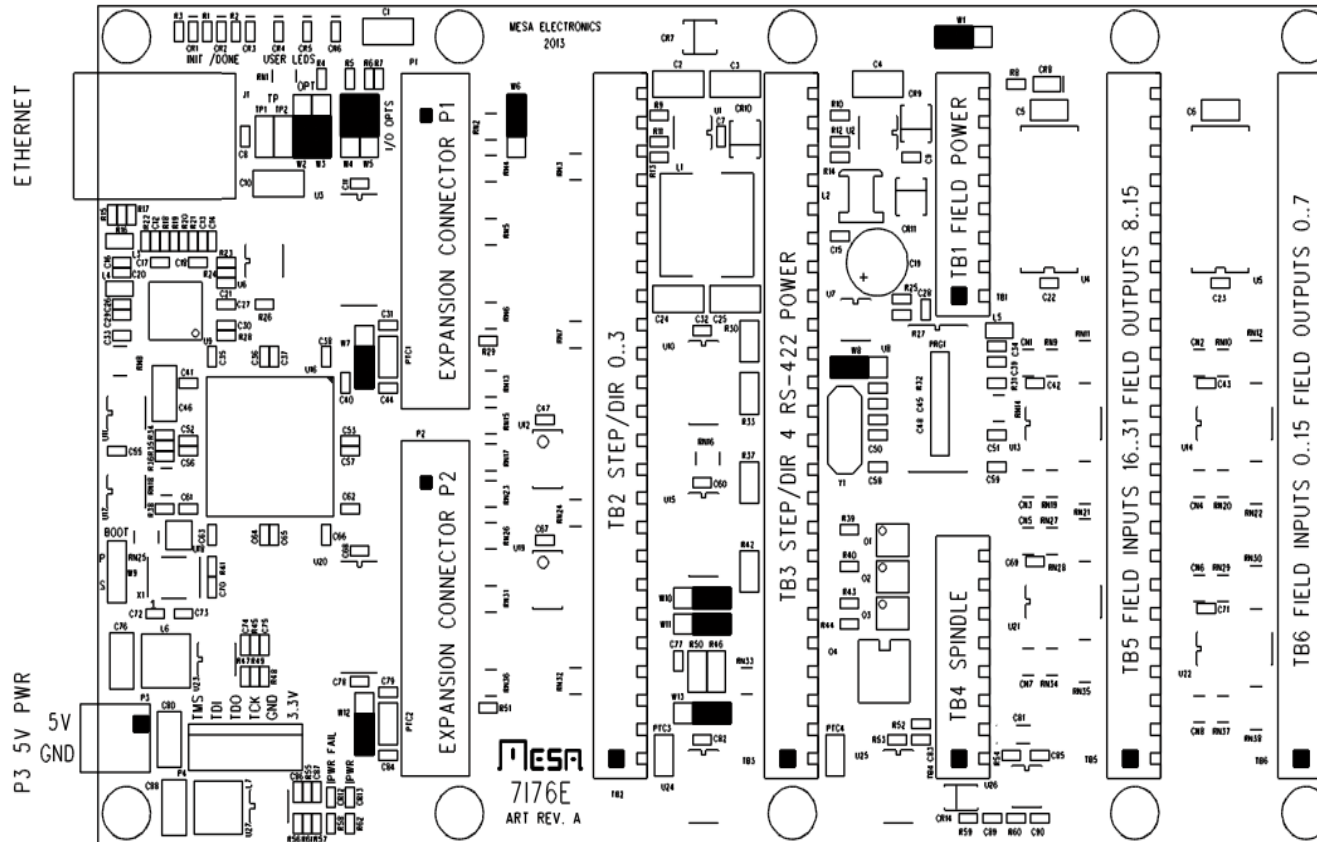
MODE 2 I/O plus analog input and field voltage and MPG mode

32 bits of input data, 16 bits of output data, 4 analog input channels, field voltage analog in,
and 2 MPG encoders on inputs 16..19.

Default encoder count mode is 1X to match normal 100 ppr MPG's.

To PC

Do not
connect



Jumpers:

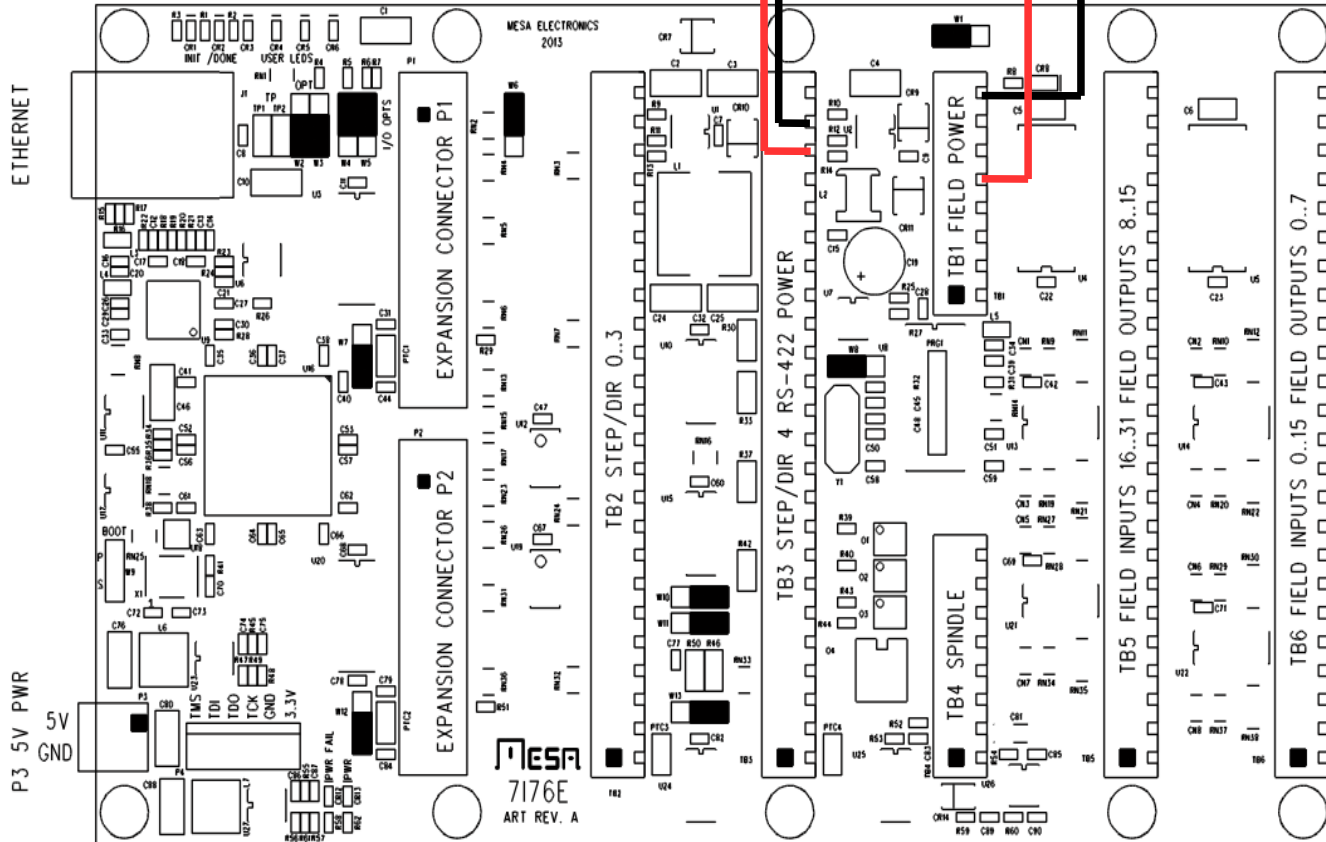
- W1 : left (default)
- W2 : down (default)
- W3 : down (default) *
- W4 : up (default)
- W5 : up (default)
- W6 : up (default)
- W7 : down (default)
- W8 : left (default)
- W9 : up (default)
- W10 : left (default)
- W11 : left (default)
- W12 : down (default)
- W13 : left (default)

* Its suggested to use the 10.10.10 IP address for LinuxCNC so you don't end up with the real time Ethernet IP address range, overlapping a DHCP pool of local network addresses. (set W3 up instead of down to use 10.10.10)

Power Connections

Do not connect

P3 5V PWR
5V
GND

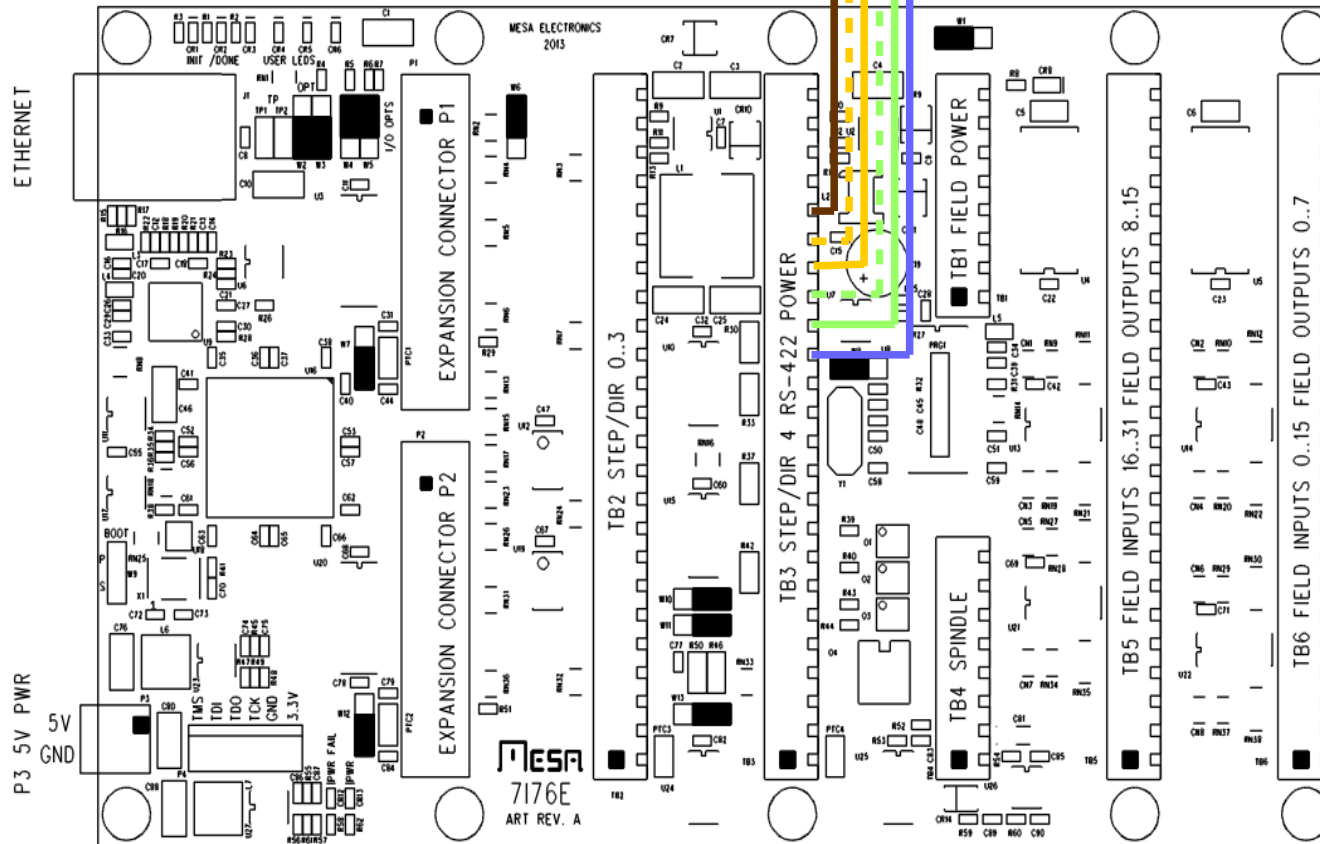


TB1 Field Power
 — Pin 8 : GND
 — Pin 5 : + 24 V

TB3 Power
 — Pin 23 : GND
 — Pin 22 : + 24 V

To SSerial Device i.E. 7i73

Connection to SSerial device, i.e. 7i73



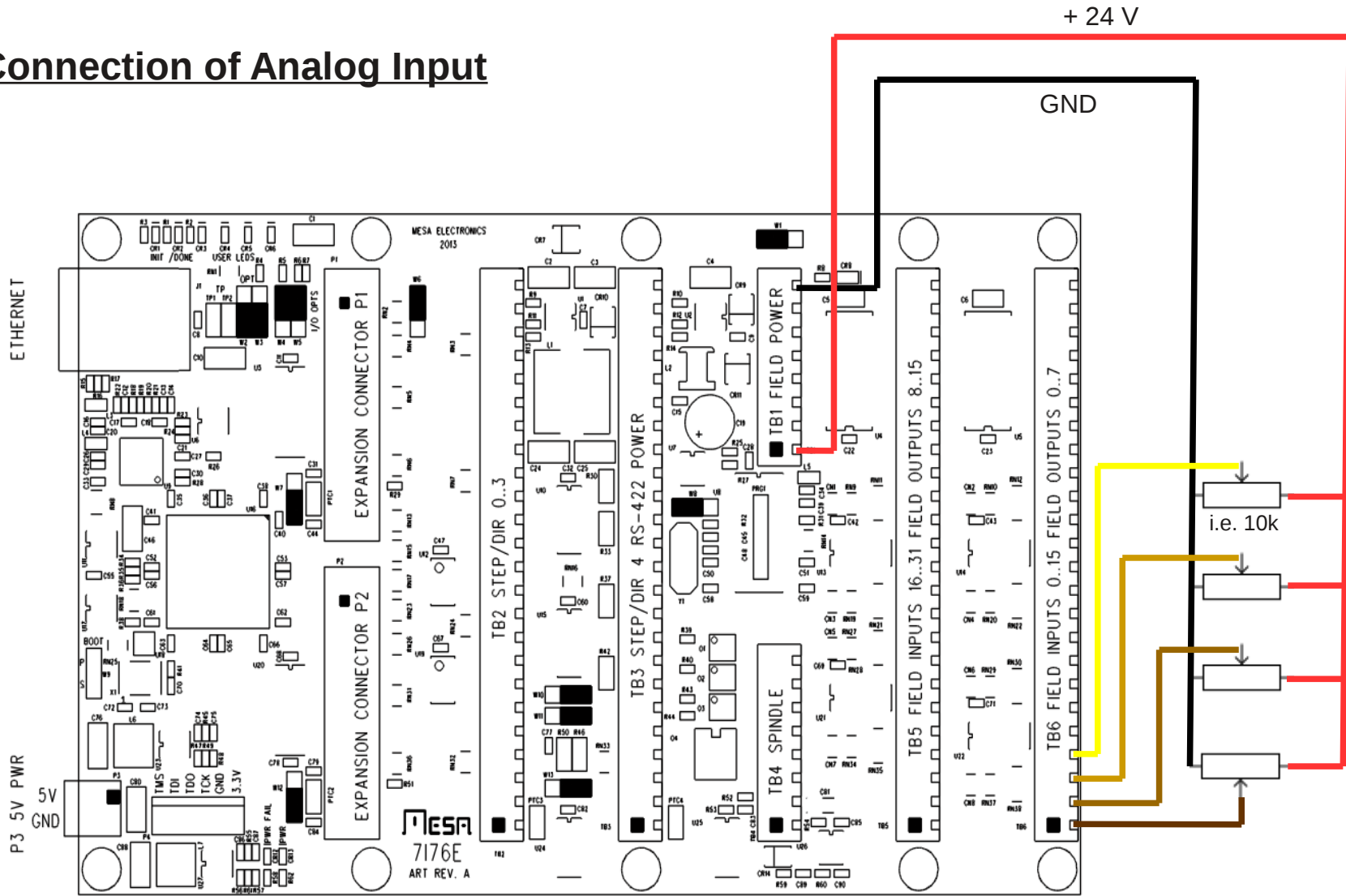
TB3 SSerial

-  Pin 20 : Brown and Brown/White
-  Pin 19 : Orange/White
-  Pin 18 : Orange
-  Pin 17 : Green/White
-  Pin 16 : Green
-  Pin 15 : Blue and Blue/White

Colors correspond to Standard CAT 5 or CAT 6 network cable
If wired according T568B
Just cut one end

For details see:
<https://en.wikipedia.org/wiki/TIA/EIA-568>

Connection of Analog Input



- TB1 Field Power**
- Pin 5 : + 24 V
- Pin 8 : GND
- Pin 1 : + 24 V

You may use also:
 Pin 5 : + 24 V
 Pin 4 : + 24 V
 Pin 3 : + 24 V
 Pin 2 : + 24 V
 as power source or get GND and +24 V directly from the powersupply.

- TB6 : Analog in**
- PIN 4 = hm2_7i76e.0.7i76.0.0.analogin3
- PIN 3 = hm2_7i76e.0.7i76.0.0.analogin2
- PIN 2 = hm2_7i76e.0.7i76.0.0.analogin1
- PIN 1 = hm2_7i76e.0.7i76.0.0.analogin0

Connection of Digital Input

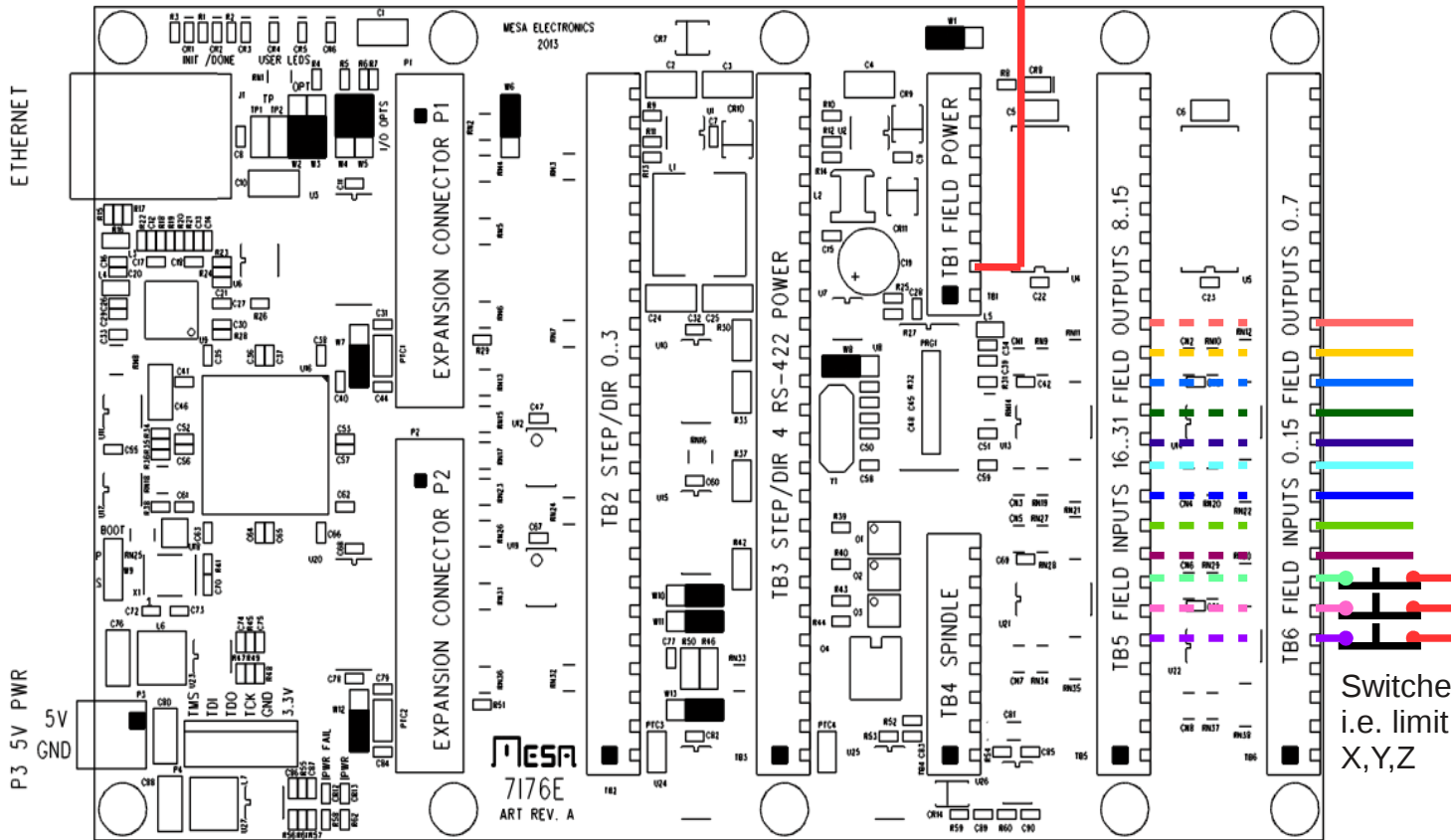
TB1 Field Power

Pin 2 : + 24 V

You may use:
 Pin 5 : + 24 V
 Pin 4 : + 24 V
 Pin 3 : + 24 V
 Pin 1 : + 24 V

as power source or
 get it directly from
 the power supply.

+ 24 V



TB6 : Digital in

- PIN 16 = hm2_7i76e.0.7i76.0.0.input-15
- PIN 15 = hm2_7i76e.0.7i76.0.0.input-14
- PIN 14 = hm2_7i76e.0.7i76.0.0.input-13
- PIN 13 = hm2_7i76e.0.7i76.0.0.input-12
- PIN 12 = hm2_7i76e.0.7i76.0.0.input-11
- PIN 11 = hm2_7i76e.0.7i76.0.0.input-10
- PIN 10 = hm2_7i76e.0.7i76.0.0.input-09
- PIN 9 = hm2_7i76e.0.7i76.0.0.input-08
- PIN 8 = hm2_7i76e.0.7i76.0.0.input-07
- PIN 7 = hm2_7i76e.0.7i76.0.0.input-06
- PIN 6 = hm2_7i76e.0.7i76.0.0.input-05
- PIN 5 = hm2_7i76e.0.7i76.0.0.input-04

Do not use
 hm2_7i76e.0.7i76.0.0.input-03
 hm2_7i76e.0.7i76.0.0.input-02
 hm2_7i76e.0.7i76.0.0.input-01
 hm2_7i76e.0.7i76.0.0.input-00
 As they are used as analog input

TB5 : Digital in

- PIN 16 = hm2_7i76e.0.7i76.0.0.input-31
- PIN 15 = hm2_7i76e.0.7i76.0.0.input-30
- PIN 14 = hm2_7i76e.0.7i76.0.0.input-29
- PIN 13 = hm2_7i76e.0.7i76.0.0.input-28
- PIN 12 = hm2_7i76e.0.7i76.0.0.input-27
- PIN 11 = hm2_7i76e.0.7i76.0.0.input-26
- PIN 10 = hm2_7i76e.0.7i76.0.0.input-25
- PIN 9 = hm2_7i76e.0.7i76.0.0.input-24
- PIN 8 = hm2_7i76e.0.7i76.0.0.input-23
- PIN 7 = hm2_7i76e.0.7i76.0.0.input-22
- PIN 6 = hm2_7i76e.0.7i76.0.0.input-21
- PIN 5 = hm2_7i76e.0.7i76.0.0.input-20

Do not use
 hm2_7i76e.0.7i76.0.0.input-19
 hm2_7i76e.0.7i76.0.0.input-18
 hm2_7i76e.0.7i76.0.0.input-17
 hm2_7i76e.0.7i76.0.0.input-16
 As they are used as MPG input

Switches
 i.e. limit
 X,Y,Z

Connection of inductive proximity sensors

TB1 Field Power

Pin 2 : + 24 V

You may use:
 Pin 5 : + 24 V
 Pin 4 : + 24 V
 Pin 3 : + 24 V
 Pin 1 : + 24 V

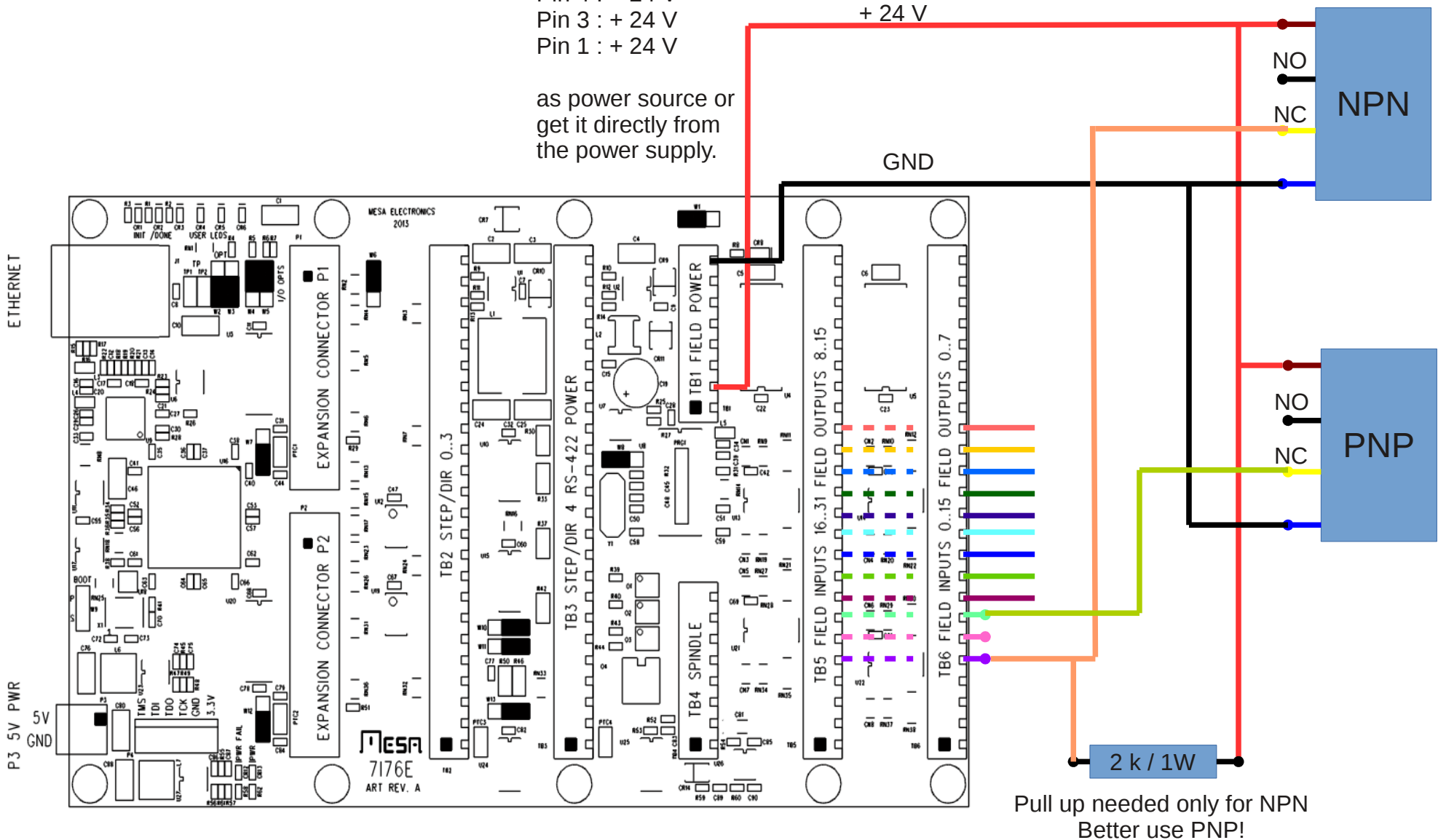
as power source or
 get it directly from
 the power supply.

TB5 : Digital in

PIN Names see previous page

TB6 : Digital in

PIN Names see previous page

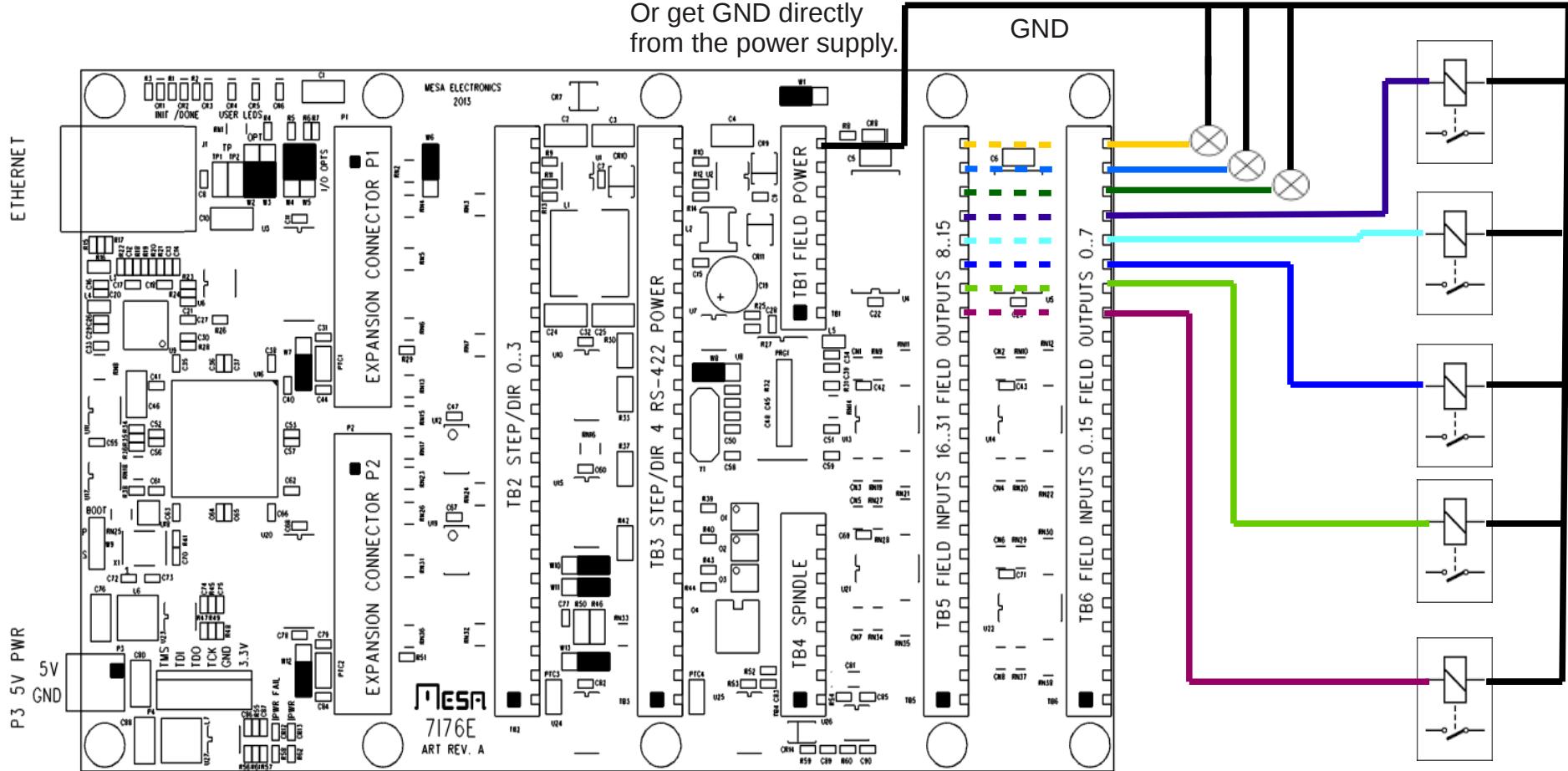


Pull up needed only for NPN
 Better use PNP!

Connection of Digital Output

TB1 Field Power
 Pin 8 : GND
 Or get GND directly from the power supply.

Important note:
 Maximum output load per pin is 350 mA
 Total output is limited to 2A.



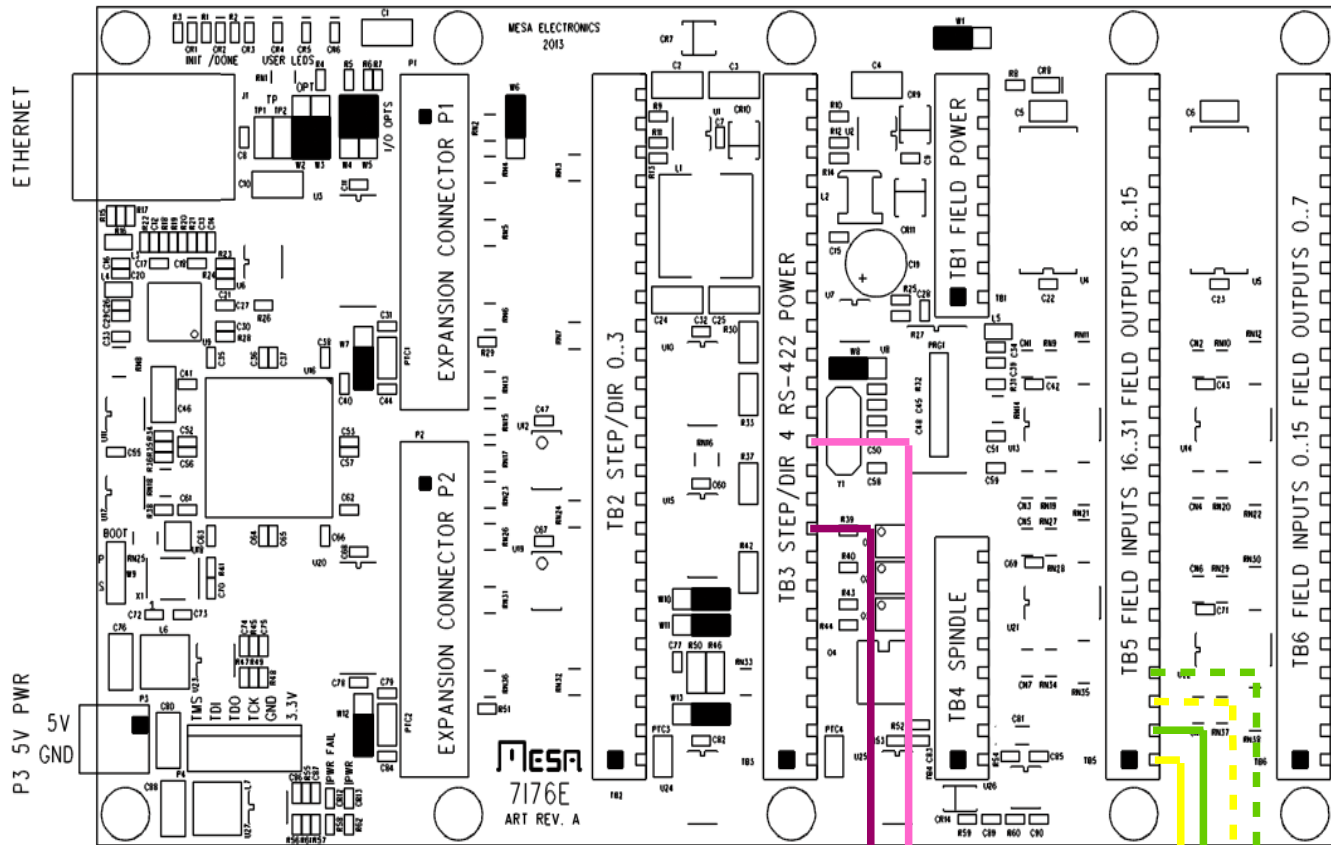
TB5 : Digital out

- ■ ■ ■ PIN 24 = hm2_7i76e.0.7i76.0.0.output-15
- ■ ■ ■ PIN 23 = hm2_7i76e.0.7i76.0.0.output-14
- ■ ■ ■ PIN 22 = hm2_7i76e.0.7i76.0.0.output-13
- ■ ■ ■ PIN 21 = hm2_7i76e.0.7i76.0.0.output-12
- ■ ■ ■ PIN 20 = hm2_7i76e.0.7i76.0.0.output-11
- ■ ■ ■ PIN 19 = hm2_7i76e.0.7i76.0.0.output-10
- ■ ■ ■ PIN 18 = hm2_7i76e.0.7i76.0.0.output-09
- ■ ■ ■ PIN 17 = hm2_7i76e.0.7i76.0.0.output-08

TB6 : Digital out

- ■ ■ ■ PIN 24 = hm2_7i76e.0.7i76.0.0.output-07
- ■ ■ ■ PIN 23 = hm2_7i76e.0.7i76.0.0.output-06
- ■ ■ ■ PIN 22 = hm2_7i76e.0.7i76.0.0.output-05
- ■ ■ ■ PIN 21 = hm2_7i76e.0.7i76.0.0.output-04
- ■ ■ ■ PIN 20 = hm2_7i76e.0.7i76.0.0.output-03
- ■ ■ ■ PIN 19 = hm2_7i76e.0.7i76.0.0.output-02
- ■ ■ ■ PIN 18 = hm2_7i76e.0.7i76.0.0.output-01
- ■ ■ ■ PIN 17 = hm2_7i76e.0.7i76.0.0.output-00

Connection of MPG's

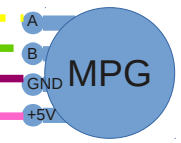


- TB5 : MPG in**
- PIN 4 = MPG 1 Signal B
 - PIN 3 = MPG 1 Signal A
 - PIN 2 = MPG 0 Signal B
 - PIN 1 = MPG 0 Signal A

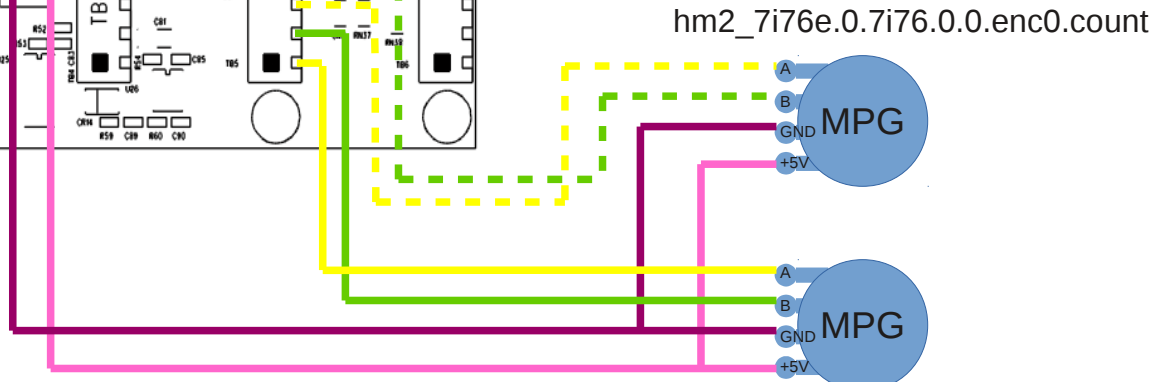
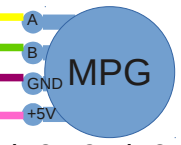
- TB3 : MPG Power**
- PIN 12 = MPG + 5V
 - PIN 9 = MPG GND

Power could also be taken from other pin i.E. TB3 Pin 1 and PIN 6

hm2_7i76e.0.7i76.0.0.enc0.count



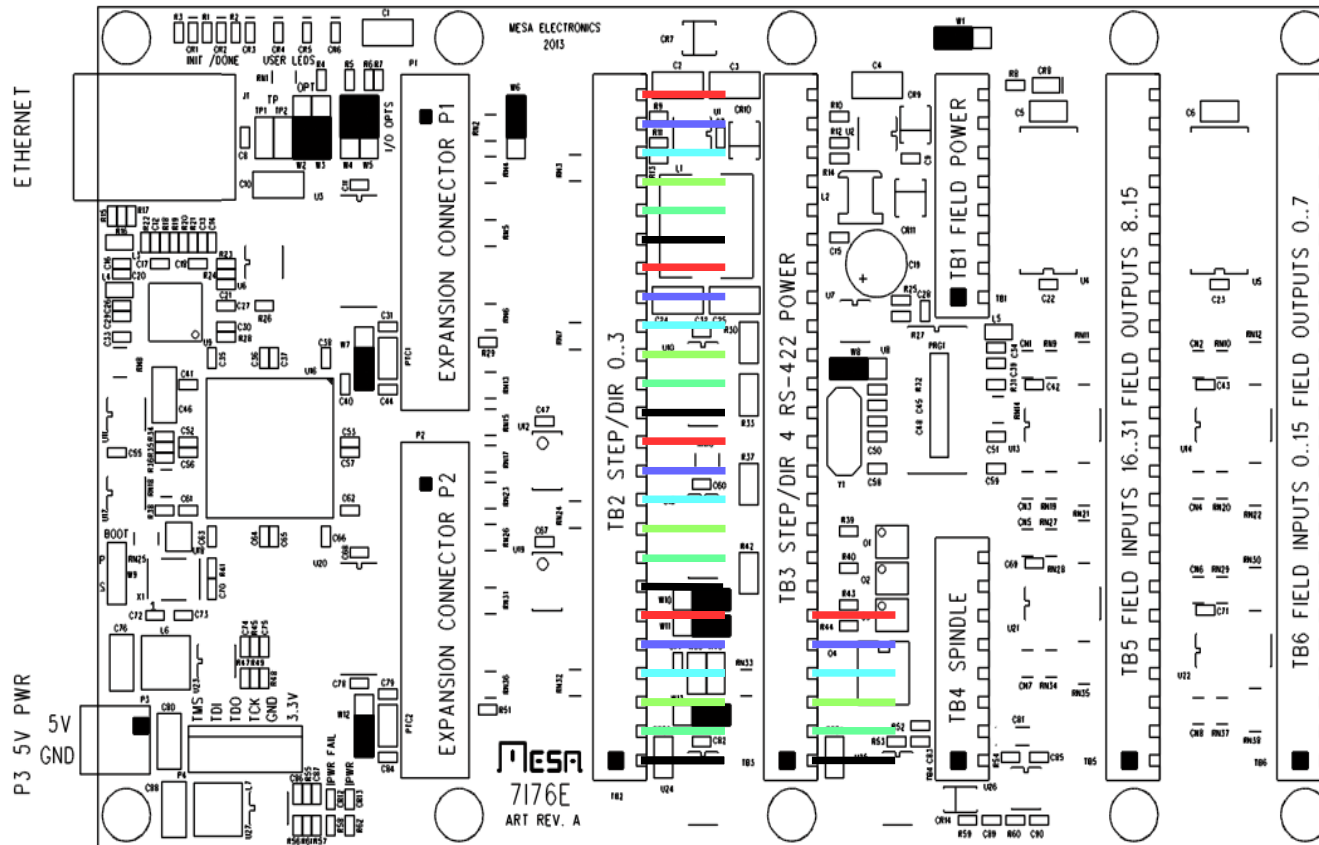
hm2_7i76e.0.7i76.0.0.enc1.count



Connection of Steppers

Note:

Not used pins can not be used as IO Pin, even if not all stepper are used



TB2 : Stepper in

- PIN 24 = + 5V : Stepper 3
- PIN 23 = DIR+ : Stepper 3
- PIN 22 = DIR- : Stepper 3
- PIN 21 = STEP+ : Stepper 3
- PIN 20 = STEP - : Stepper 3
- PIN 19 = GND : Stepper 3

- PIN 18 = + 5V : Stepper 2
- PIN 17 = DIR+ : Stepper 2
- PIN 16 = DIR- : Stepper 2
- PIN 15 = STEP+ : Stepper 2
- PIN 14 = STEP - : Stepper 2
- PIN 13 = GND : Stepper 2

- PIN 12 = + 5V : Stepper 1
- PIN 11 = DIR+ : Stepper 1
- PIN 10 = DIR- : Stepper 1
- PIN 9 = STEP+ : Stepper 1
- PIN 8 = STEP - : Stepper 1
- PIN 7 = GND : Stepper 1

- PIN 6 = + 5V : Stepper 0
- PIN 5 = DIR+ : Stepper 0
- PIN 4 = DIR- : Stepper 0
- PIN 3 = STEP+ : Stepper 0
- PIN 2 = STEP - : Stepper 0
- PIN 1 = GND : Stepper 0

TB3 : Stepper in

- PIN 6 = + 5V : Stepper 4
- PIN 5 = DIR+ : Stepper 4
- PIN 4 = DIR- : Stepper 4
- PIN 3 = STEP+ : Stepper 4
- PIN 2 = STEP - : Stepper 4
- PIN 1 = GND : Stepper 4

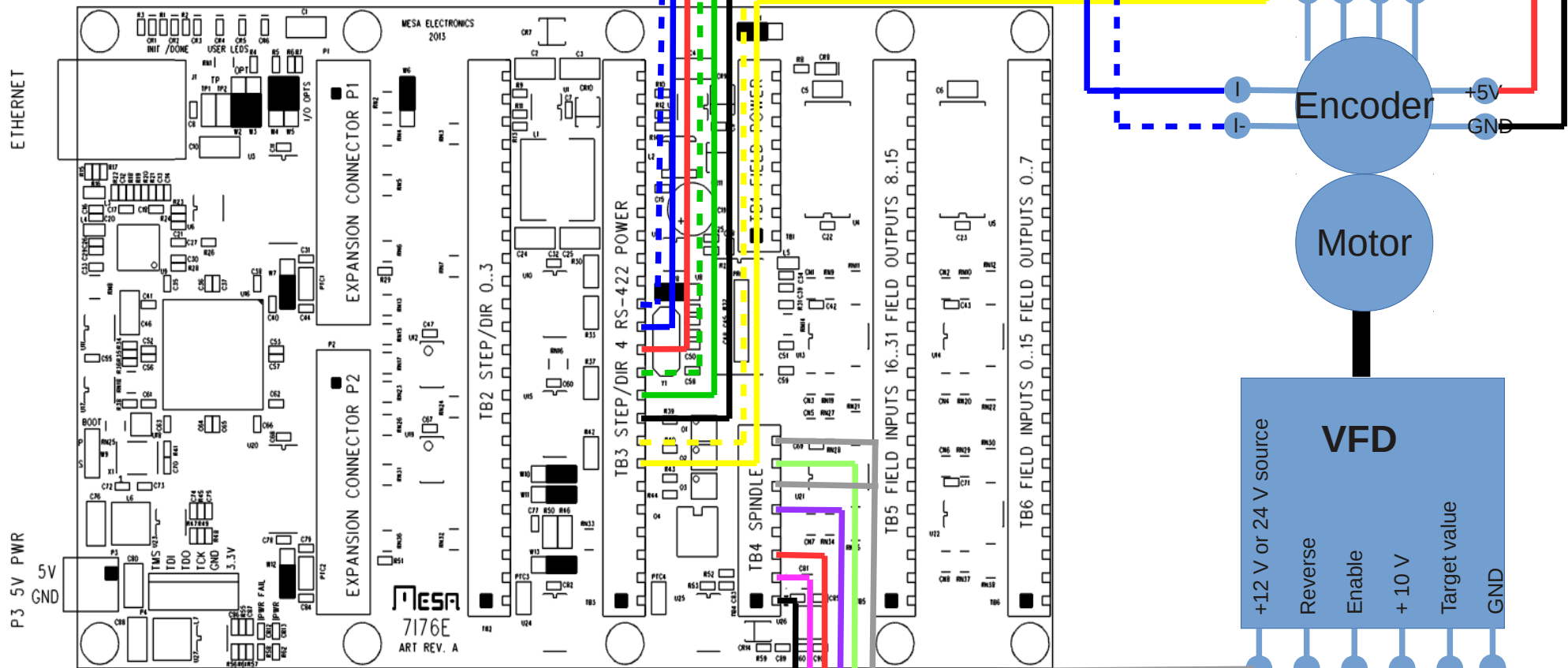
Type 0	Type2
— + 5 V	+ 5 V
— DIR +	A
— DIR -	A-
— STEP +	B
— STEP -	B-
— GND	GND

```
setp hm2_7i76e.0.stepgen.00.step_type 0
```

Sets the type to be used:
 Type 0 = step/dir
 Type 1 = up/down
 Type 2 = quadratur A/B
 Type 3 = Three phase full step
 Etc.

See „man stepgen“ for all details

Connection of Spindle



TB3 : Encoder

- - - PIN 14 = Index -
- PIN 13 = Index
- PIN 12 = + 5 V
- - - PIN 11 = B -
- PIN 10 = B
- PIN 9 = GND
- - - PIN 8 = A-
- PIN 7 = A

TB4 : Spindle

- PIN 8 = Spindle DIR +
- PIN 7 = Spindle DIR -
- PIN 6 = Spindle Enable +
- PIN 5 = Spindle Enable -
- PIN 4 = not connected
- PIN 3 = Spindle +
- PIN 2 = Spindle OUT
- PIN 1 = Spindle -

hm2_7i76e.0.7i76.0.0.spindir
 hm2_7i76e.0.7i76.0.0.spinena
 hm2_7i76e.0.7i76.0.0.spinout