

Content	Register	Function
	bit 8	1: Master frequency controlled by communication interface
	bit 9	1: Master frequency controlled by analog signal
	bit 10	1: Operation command controlled by communication interface
	bit 11	1: Parameter locked
	bit 12	1: Enable to copy parameters from keypad
	bit 15~13	Reserved
	2102H	Frequency command (XXX.XX Hz)
	2103H	Output frequency (XXX.XX Hz)
	2104H	Output current (XX.XX A). When current is higher than 655.35, it will shift decimal as (XXX.X A). The decimal can refer to High byte of 211F.
	2105H	DC-BUS voltage (XXX.X V)
	2106H	Output voltage (XXX.X V)
	2107H	Current step number of multi-stage speed operation
	2108H	Reserved
	2109H	Counter value
	210AH	Power factor angle (XXX.X)
	210BH	Output torque (XXX.X %)
	210CH	Actual motor speed (XXXXX rpm)
	210DH	Number of PG feedback pulses (0~65535)
	210EH	Number of PG2 pulse commands (0~65535)
	210FH	Power output (X.XXX KWH)
	2116H	Multi-function display (Pr. 00-04)
	211BH	Max. operation frequency (Pr. 01-00) or Max. user defined value (Pr. 00-26) When Pr. 00-26 is 0, this value is equal to Pr. 01-00 setting When Pr. 00-26 is not 0, and the command source is Keypad, this value = Pr. 00-24 * Pr. 00-26 / Pr. 01-00 When Pr. 00-26 is not 0, and the command source is 485, this value = Pr. 09-10 * Pr. 00-26 / Pr. 01-00
	211FH	High byte: decimal of current value (display)
	2200H	Display output current (A). When current is higher than 655.35, it will shift decimal as (XXX.X A). The decimal can refer to High byte of 211F.
	2201H	Display counter value (c)
	2202H	Actual output frequency (XXXXX Hz)
	2203H	DC-BUS voltage (XXX.X V)
	2204H	Output voltage (XXX.X V)
	2205H	Power angle (XXX.X)
	2206H	Display actual motor speed kW of U, V, W (XXXXX kW)
	2207H	Display motor speed in rpm estimated by the drive or encoder feedback (XXXXX rpm)
	2208H	Display positive / negative output torque in %, estimated by the drive (t0.0: positive torque, -0.0: negative torque) (XXX.X %)
	2209H	Display PG feedback (as Pr. 00-04 NOTE 1)
	220AH	PID feedback value after enabling PID function (XXX.XX %)
	220BH	Reserved
	220CH	Display signal of ACI analog input terminal, 4-V20 mA / 0-10 V corresponds to 0.00~100.00% (2.) (as Pr. 00-04 NOTE 2)
	220DH	Reserved
	220EH	IGBT temperature of drive power module (XXX.X °C)
	220FH	The temperature of capacitance (XXX.X °C)
	2210H	The status of digital input (ON / OFF), refer to Pr. 02-12 (as Pr. 00-04 NOTE 3)