

Content	Register	Function
	2211H	The status of digital output (ON / OFF), refer to Pr. 02-18 (as Pr. 00-04 NOTE 4)
	2212H	The multi-step speed that is executing (S)
	2213H	The corresponding CPU pin status of digital input (d.) (as Pr. 00-04 NOTE 3)
	2214H	The corresponding CPU pin status of digital output (O.) (as Pr. 00-04 NOTE 4)
	2215H	Number of actual motor revolution (PG1 of PG card) (P.) it will start from 9 when the actual operation direction is changed or keypad display at stop is 0. Max. is 65535
	2216H	Pulse input frequency (PG2 of PG card) (XXX.XX Hz)
	2217H	Pulse input position (PG card PG2), maximum setting is 65535.
	2218H	Position command tracing error
	2219H	Display times of counter overload (XXX.XX %)
	221AH	GFF (XXX.XX %)
	221BH	DCbus voltage ripples (XXX.X V)
	221CH	PLC register D1043 data (C)
	221DH	Pole of Permanent Magnet Motor
	221EH	User page displays the value in physical measure
	221FH	Output Value of Pr. 00-05 (XXX.XX Hz)
	2220H	Number of motor turns when drive operates (keeping when drive stops, and reset to zero when operation)
	2221H	Operation position of motor (keeping when drive stops, and reset to zero when operation)
	2222H	Fan speed of the drive (XXX %)
	2223H	Control mode of the drive 0: speed mode 1: torque mode
	2224H	Carrier frequency of the drive (XX KHZ)
	2225H	Reserved
	2226H	Drive status bit 1~0 00b: No direction 01b: Forward 10b: Reverse bit 3~2 01b: Driver ready 10b: Error bit 4 0b: Motor drive did not output 1b: Motor drive did output bit 5 0b: No alarm 1b: Have Alarm
	2227H	Drive's estimated output torque (positive or negative direction) (XXXX Nt-m)
	2228H	Torque command (XXX.X %)
	2229H	KWH display (XXXX.X)
	222AH	MI7pulse input in Low Word
	222BH	MI7 pulse input in High Word
	222CH	Motor actual position in Low Word
	222DH	Motor actual position in High Word
	222EH	PID reference (XXX.XX %)
	222FH	PID offset (XXX.XX %)
	2230H	PID output frequency (XXX.XX Hz)
	2231H	Hardware ID
	2232H	Display auxiliary frequency
	2233H	Display master frequency
	2234H	Display frequency after addition and subtraction of auxiliary and master frequency