

# Initial OS Installation

Friday, January 3, 2025

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1. Use the Raspberry Pi Imager to clone <https://www.linuxcnc.org/iso/rpi-5-debian-bookworm-6.1.61-rt15-arm64-ext4-2023-11-17-1520.img.xz> to your SD Card.
2. Boot the Pi with keyboard attached (username: cnc password: cnc)
3. Change the device hostname (if needed)  
[`sudo hostnamectl set-hostname "name-here"`]  
Update the hosts file (change any occurrences of "old-hostname" to "new-hostname" and save the file.  
[`sudo nano /etc/hosts`]
4. Enable wireless with the following cmd (if needed)  
[`sudo nmcli d wifi connect "ssid_here" password "password_here" ifname wlan0`]
5. Change password (if needed)  
[`passwd`]
6. Run the following to install updates  
[`sudo apt update -y | sudo apt dist-upgrade -y`]
7. Enable the SPI overlay in config.txt (located in /boot/broadcom/) change the following line from  
[`#dtparam=spi=on`]  
to  
[`dtparam=spi=on`]  
  
Validate SPI is enabled (after a reboot)  
[`ls /dev/spi*`]  
If you do not see 3 devices (listed below), something is wrong and you need to troubleshoot enabling SPI  
{`spidev0.0 spidev0.1 spidev10.0`}

## Build MesaFlash (validate card communication)

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Follow the current build instructions:

<https://github.com/LinuxCNC/mesaflash>

1. Install these dependencies  
[`sudo apt install libpci-dev libmd-dev pkg-config build-essential git`]
2. Create a directory for sources  
[`mkdir sources`]

3. Change to the directory  
[cd sources]
4. Clone the repo locally  
[git clone <https://github.com/LinuxCNC/mesaflash.git>]
5. Change to the mesaflash directory  
[cd mesaflash]
6. Run Make to build the program  
[make]
7. To build and install from source  
[sudo make install]

Validate card communication:

**NOTE: Card must be connected via the 40pin GPIO cable (1.5in length, 2" absolute Max length)**  
**NOTE: Card must be powered externally (not via the Pi cable)**

1. Run MesaFlash to verify communication to the card (7c80 & 7c81)  
for 7c80:  
[sudo mesaflash --device 7c80 --addr /dev/spidev0.0 --spi --readhmid]  
for 7c81:  
[sudo mesaflash --device 7c81 --addr /dev/spidev0.0 --spi --readhmid]

You should get output similar to below. If not, stop here and troubleshoot SPI connectivity / driver issues.  
**Configuration Name: HOSTMOT2**

**General configuration information:**

**BoardName : MESA7C80**  
**FPGA Size: 9 KGates**  
**FPGA Pins: 144**

If this is successful, continue on to the LinuxCNC build steps

## Build LinuxCNC from Source

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Current build instructions are located here: <https://linuxcnc.org/docs/devel/html/code/building-linuxcnc.html>

1. Change directories to the Sources directory that you created earlier  
[ cd ~/sources ]

2. Clone the github repo:

[ git clone <https://github.com/LinuxCNC/linuxcnc.git> linuxcnc-source-dir ]

3. Install the required build tools

[ sudo apt-get install build-essential ]

4. Change to the "linuxcnc-source-dir" sub-directory

[ cd linuxcnc-source-dir/ ]

5. Run the following to install build dependencies

[ dpkg-checkbuilddeps ]

NOTE: Install any missing packages, keep re-running the previous command to check for missing packages

[ sudo apt build-dep . . ]

Once no missing packages are found, you may continue

6. Set the following variable (for controlling the package build), and build the package.

Without Docs - [DEB\_BUILD\_OPTIONS=nodocs,nocheck dpkg-buildpackage -uc -B -j6 ]

7. Run the following command to install the packages that you just built.

[ sudo dpkg -i ../linuxcnc\*.deb ]